



**International Cartographic
Association Working Group
on Cartography and
Sustainable Development**



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Objectives of the Presentation

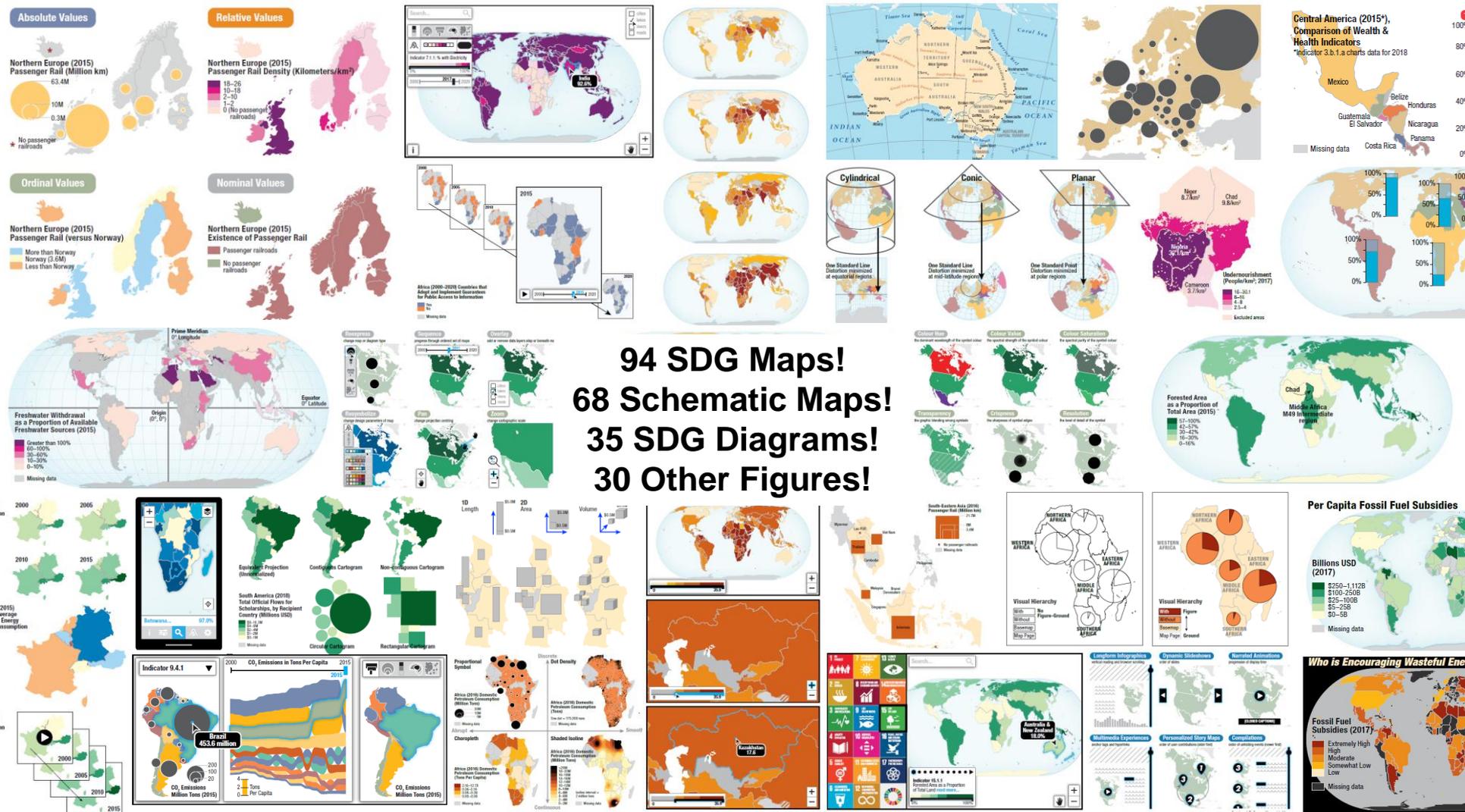
- The power of cartography
- Many options and choices to make for effective communication
- Maps as a catalyst for acting on the SDGs
- Maps show data for areas of interest
 - Absence of data can highlight where data are needed

Map Design Considerations

Cartography = Art + Science of map making



Mapping for a Sustainable World



94 SDG Maps!
68 Schematic Maps!
35 SDG Diagrams!
30 Other Figures!



MAPPING

FOR A SUSTAINABLE WORLD

MAPPING

FOR A SUSTAINABLE WORLD



Outline:

- 1. SDGs & Geospatial Data**
“How to think about the SDGs like a cartographer”
- 2. Map Design Considerations**
“10 ways to make more effective maps today”
- 3. Maps & Effect**
“What are the maps communicating?”
- 4. Tutorial...find data...**

The book consists of **four sections**. Section 1 introduces the SDGs and their relation to geospatial data. Section 2 describes foundational design decisions in the cartographic workflow. Section 3 introduces the most relevant map types and diagrams for visualizing the SDG indicators. Finally, Section 5 discusses considerations for map use environments.

1. SDGs & Geospatial Data

- 1.1 The United Nations Sustainable Development Goals
- 1.2 Geospatial Data
- 1.3 Location Data: Representing the World
- 1.4 Attribute Data: SDG Indicators & Levels of Measurement
- 1.5 Temporal Data: Representing Change
- 1.6 Indicator Tiers & their Data Characteristics
- 1.7 Data Transformation & Normalisation
- 1.8 The Modifiable Areal Unit Problem & the Ecological Fallacy
- 1.9 Data Classification

2. Map Design Considerations

- 2.1 Content Selection
- 2.2 Project Planning & the Design Process
- 2.3 Cartographic Design Decisions
- 2.4 Map Projections
- 2.5 Projection Centring
- 2.6 Cartographic Scale
- 2.7 Generalisation
- 2.8 Dimensionality
- 2.9 Symbolisation & the Visual Variables
- 2.10 Colour
- 2.11 Typography
- 2.12 Toponymy
- 2.13 Layout & Visual Hierarchy
- 2.14 Art & Style
- 2.15 Missing Data & Representing Uncertainty

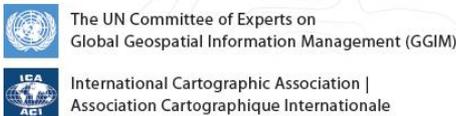
3. Maps & Diagrams

- 3.1 Thematic Maps
- 3.2 Nominal Maps
- 3.3 Choropleth Maps
- 3.4 Proportional Symbol Maps
- 3.5 Dasymetric Maps
- 3.6 Map Legends
- 3.7 Bivariate Maps
- 3.8 Cartograms
- 3.9 Maps & Time
- 3.10 Diagrams
- 3.11 Diagrams of a Single Attribute
- 3.12 Diagrams for Comparisons within an Attribute
- 3.13 Diagrams for Multiple Indicators
- 3.14 Diagrams of a Single Attribute over Time

4. Map Use Environments

- 4.1 Audiences
- 4.2 Accessibility & Visual Impairment
- 4.3 Interactive Maps
- 4.4 Interaction Operators
- 4.5 Web Maps
- 4.6 Mobile Maps & Responsive Design
- 4.7 Storytelling
- 4.8 Animation
- 4.9 Dashboards
- 4.10 Exploratory Visualisation
- 4.11 Atlases
- 4.12 Usability
- 4.13 Open Access

A JOINT PUBLICATION OF



How spatial indicators are collected and then mapped

Phases of GIS Data Flow

Phase 1.

Phase 2.

Phase 3.

Phase 4.



Observing the
World

*Data Abstraction
Collection
Entry*

*Data Storage
Aggregation
Analysis*

*Information Dissemination
Data Visualization
Map*



UNITED NATIONS Geospatial

Working Group on GeoVisualization



3.1 Thematic Maps

A *thematic map* depicts the variation of one or sometimes several (see [Section 3.7](#)) geographic phenomena, mapping spatial and attribute information together. Meeting the United Nations Sustainable Development Goals requires themat-

[Section 1.4](#)). Enumerated attributes typically are mapped at an ordinal or numerical level of measurement, as enumeration results in quantitative counts or frequencies. However, nominal differences also can be represented in thematic

Thematic Map

A map that depicts variation in one or several attributes

the mode or binary value (presence, yes/no), resulting in a *nominal map* (see [Section 3.2](#)). A thematic map type symbolises using a different visual [Section 2.9](#)). For instance, a *map* (see [Section 3.3](#)) shades

attribute information that is enumerated within polygonal geographic units (see

enumeration units by their attribute values, primarily relying on colour value.

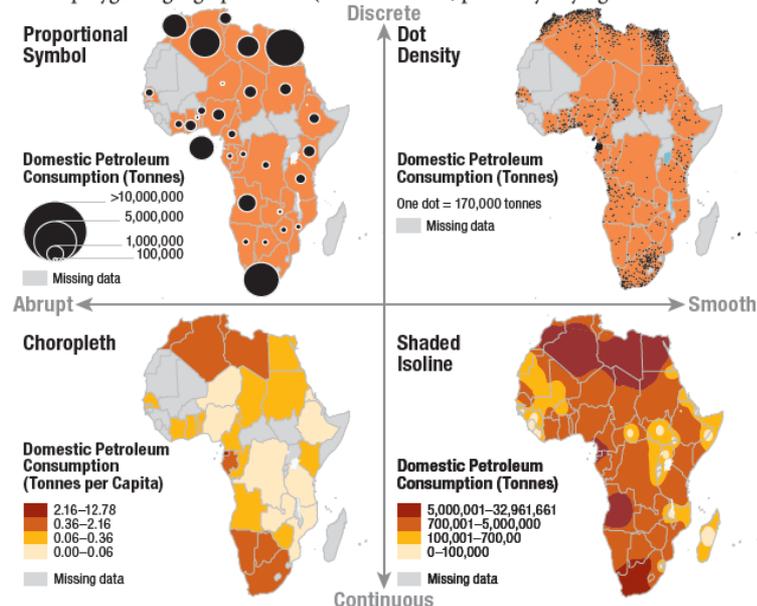


Figure 3.1-1: Thematic map types. The four maps depict Indicator 12.2.2 (2016) on domestic petroleum consumption. **Top-left:** Proportional Symbol. **Top-right:** Dot density. **Bottom-left:** Choropleth. **Bottom-right:** Shaded isoline.

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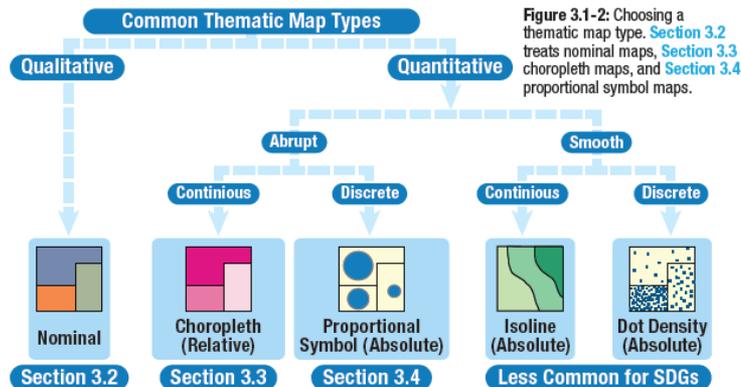


Figure 3.1-2: Choosing a thematic map type. [Section 3.2](#) treats nominal maps, [Section 3.3](#) choropleth maps, and [Section 3.4](#) proportional symbol maps.

A *proportional symbol map* (see [Section 3.4](#)) uses the visual variable size to scale point symbols placed at the centroids of enumeration units by their attribute values. A *dot density map* (different from dot maps; see [Section 3.2](#)) uses the composite visual variable *numerousness* (arrangement combined with size) to adjust the density of dots placed within enumeration units by their attribute values. Finally, an *isoline map* interpolates attribute values from the centroids of enumeration units, using the visual variable location to represent the interpolated attribute gradient atop spatial locations.

Each thematic map type also evokes a different *visual metaphor* about the mapped geographic phenomenon, leading to different framings of and conclusions about the same attribute data. Visual metaphors are particularly pertinent when mapping enumerated data like the SDG indicators because information about how the phenomenon exists within space (discrete versus

vs. continuous) and varies across space (abruptly vs. smoothly) is lost during enumeration ([Figure 3.1-1](#)). Choropleth maps evoke a metaphor of continuous and abrupt phenomena, such as governmental activities, policies, and regulations fixed to political jurisdictions (i.e., enumeration units). Proportional symbol maps evoke a discrete and abrupt metaphor, suggesting economic sites of production and distribution like mines, factories, offices, and stores. Dot density maps evoke a discrete and smooth metaphor, suggesting the individual bodies of human and social phenomena. Isoline maps evoke a continuous and smooth metaphor, suggesting environmental or geophysical phenomena.

[Figure 3.1-2](#) provides guidance for choosing a thematic map type. Dot density and isoline maps are used infrequently for the national-level indicator datasets given difficulty in reliably depicting smoothly changing patterns at coarser levels of enumeration.

The United Nations Sustainable Development Goals 65

The boundaries and names shown and the designations used on this map do not imply official endorsement or acceptance by the United Nations.



Level of Measurement	Absolute/Relative	Attributes	Mappable Values	Example	
ratio	absolute (one value)	one attribute	absolute value	count X	
	relative (calculated using two or more attributes)	one attribute	proportion	proportion of total population	% of total population
				other proportion	% of X, other than population
		two attributes	rate	rate per capita	count X per capita/population
				change rate (per time unit)	% change or count X per time
	many attributes	index (calculated)	formula		
interval			interval value	not used for SDGs	
ordinal			ordinal value	level or rank	
nominal			nominal value	presence/absence	

of measure-
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ure 1.4-2).
ta, ratio-level
both absolute and
tributes are mea-
reported with-
other attributes.
e normalized based
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(a percentage),
to two different
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multiple
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Ratio-level SDG indicators include both absolute and relative attributes. Absolute attributes often are described as “raw” data, and need to be converted to relative attributes through *normalisation* (see [Section 1.7](#)).

Many enumerated SDG indicators already are reported as proportions or rates related to population. However, population and other enumerated attributes rarely are evenly distributed within the enumeration units. Normalising ratio-level data is useful both to mask

Level of Measurement
The scale on which the attribute data is collected

one attribute	absolute value	count X	
one attribute	proportion	proportion of total population	% of total population
		other proportion	% of X, other than population
two attributes	rate	rate per capita	count X per capita/population
		change rate (per time unit)	% change or count X per time
		other rate	X per Y, other than population or time

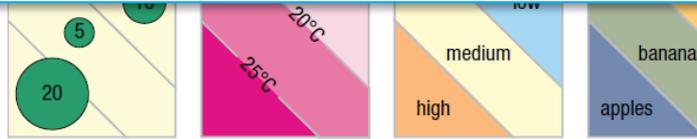
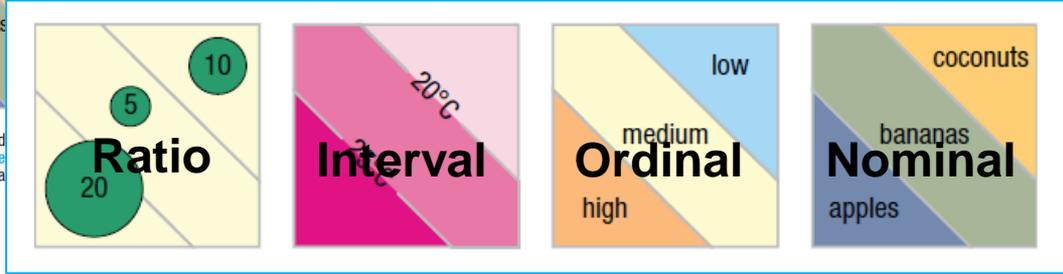


Figure 1.4-1: Attribute levels of measurement and associated example symbolisation (Left to Right): Ratio data mapped with a proportional symbol map (see [Section 3.4](#)), interval data mapped with an isoline map (see [Section 3.1](#)), ordinal data mapped with a choropleth map (see [Section 3.3](#)), and nominal data mapped with a nominal map (see [Section 3.2](#)).



1.7 Data Transformation &

Normalisation

Data transformation describes the statistical conversion of an attribute, including a downgrade in level of measurement or normalisation of absolute values into relative values (see Section 1.4).

and ordinal values into nominal values. Comparing a subset of the population to a count of the population results in a proportion (e.g., percentage of elderly). Comparing the same population

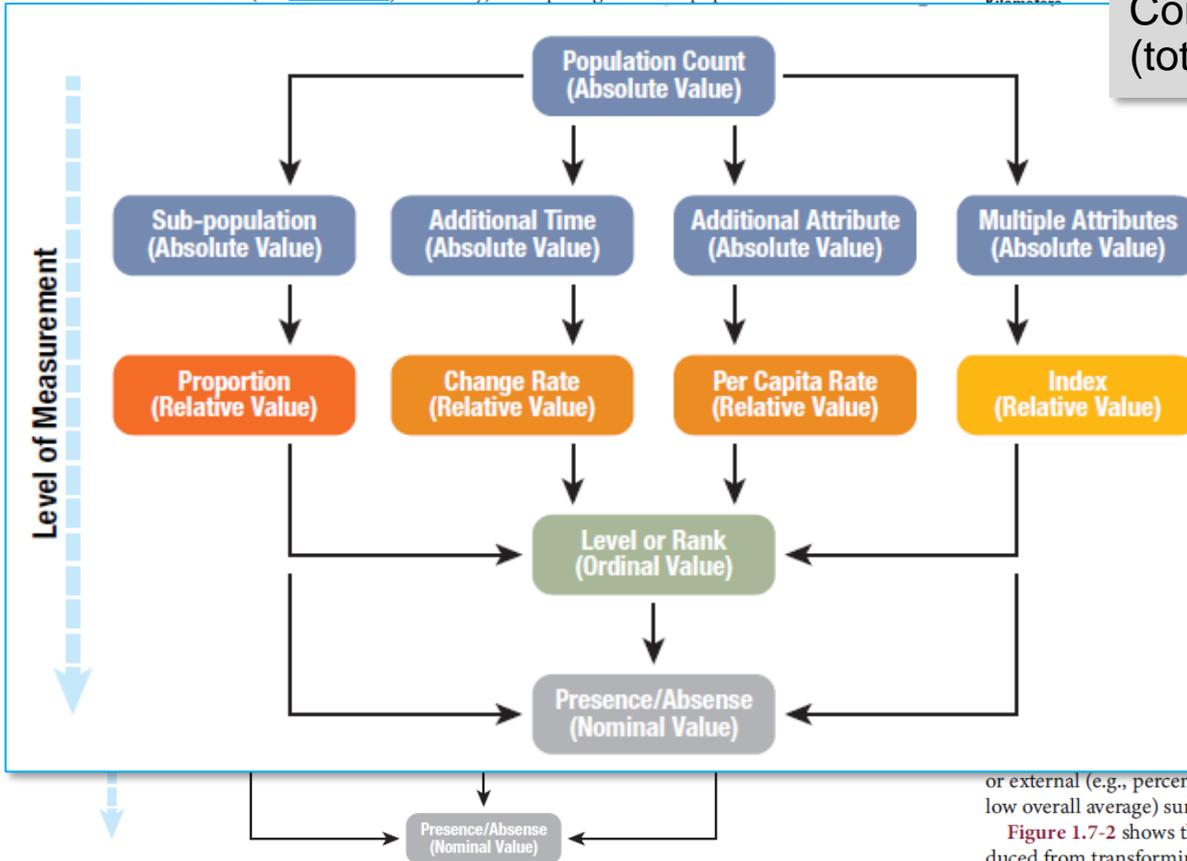
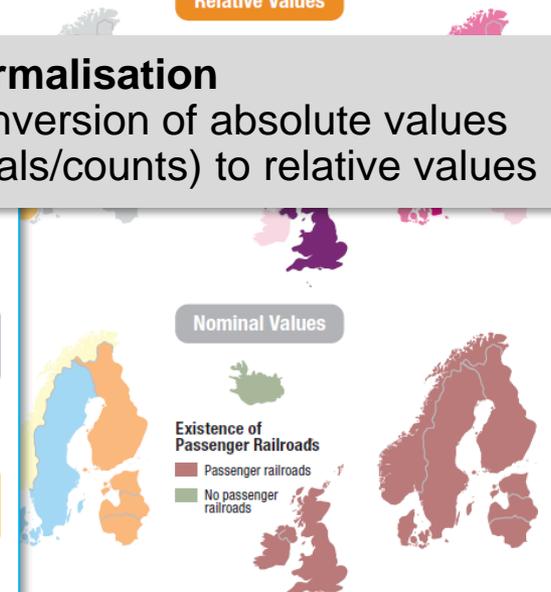


Figure 1.7-1: Data conversion options for enumerated, population-based attributes.

Absolute Values

Relative Values

Normalisation
Conversion of absolute values (totals/counts) to relative values



for Indicator 9.1.2. (2015) on passenger rail volume. Top-left: Absolute values
it: Normalised relative values / passenger rail in km per the country's total km²
(rank relative

However, absolute relative values are not suitable for mapping as they are not normalized. Calculating an index, mode

or external (e.g., percentage above/low overall average) summary value

Figure 1.7-2 shows the maps produced from transforming Indicator on passenger rail volume from absolute

The boundaries and names shown and the des

Tier 1 Indicator Mappable Values

- Absolute value
- Proportion
- Rate
- Index
- Ordinal value
- Nominal value
- Tier 2 or Pending Indicator

Indicator

t1...tn

goal

Target

t1...tn



1.9 Data Classification

Classification describes the process of organizing map features into groups to improve legibility in the representation. Classification is one of the ways in which cartographers generalise thematic maps, reducing visual complexity in the attribute data to clarify map patterns (see Section 2.7). However, classification also

ations to arrive at an appropriate *classification scheme*, such as the portion of the distribution the cartographer wishes to emphasise, the total number of classes (with most schemes using four to seven classes), and critical values that produce rounded or meaningful class breaks.

For SDG indicators reported as

Classification

The process of organizing map features into groups to improve legibility in the map

ordinal and nominal values (e.g., the **Figure 1.7-2** ordinal map reclassifies all unique rankings to show only the ranking above and below Norway's value). Classification grows in difficulty when applied to numerical data. As with all aspects of cartographic design, a perfect classification does not exist, and all classifications have trade-offs. Instead, cartographers weigh several consider-

distributions, including *arithmetic* or *geometric* for skewed attribute distributions, *equal interval* for uniform attribute distributions (**Figure 1.9-2**), *optimal breaks* for multimodal attribute distributions (**Figure 1.9-3**), and *mean & standard deviation* for normal attribute distributions (**Figures 1.9-4**).

A *quantile scheme* is useful for comparing multiple indicators that are on dif-

ferent scales or for ordinal level attributes (**Figure 1.9-5**). **Figures 1.9-2, 1.9-3, 1.9-4, and 1.9-5** incorrectly reclassify the **Figure 1.9-1** data, showing how the classification impacts the resulting map.

Because many of the SDG indicators exhibit a left- or right-skew in their attribute distribution—with many countries clustering together on one end of the

scale with several extreme outliers—the arithmetic scheme currently is common for SDG indicator data. However, if extreme global inequities are mitigated in the future, the SDG indicator data will exhibit a more uniform or normal data distribution, leading to increased use of the equal interval and mean & standard deviation classification schemes.

Figure 1.9-2: Equal interval. Equal interval places class breaks equidistant from each other. Use equal interval for indicators with a uniform distribution. Equal interval has the added advantage of resulting in simple, easy to understand map legends good for general audiences.

Annual Mean Level of Urban Fine PM ($\mu\text{g}/\text{m}^3$)

- 80.0–99.5
- 60.0–80.0
- 40.0–60.0
- 20.0–40.0
- 5.8–20.0

Missing data

Figure 1.9-3: Optimal breaks. Optimal breaks treats classes like clusters, minimising differences within the class while maximising differences among classes. Use optimal breaks for indicators with multiple clusters in the distribution or to emphasise outliers (e.g., **Figure 1.8-2**).

Annual Mean Level of Urban Fine PM ($\mu\text{g}/\text{m}^3$)

- 60.1–99.5
- 39.8–60.1
- 26.6–39.8
- 15.7–26.6
- 5.8–15.7

Missing data

Figure 1.9-4: Mean & standard deviation. Mean & standard deviation is a variation of equal interval in which the equal interval is in standard deviations from the mean. Use mean & standard deviation for indicators with a normal distribution or when the mean value is meaningful.

Annual Mean Level of Urban Fine PM ($\mu\text{g}/\text{m}^3$)

- 59.4–99.5
- 42.9–59.4
- 25.7–42.9
- 9.2–25.7
- 5.8–9.2

Missing data

Figure 1.9-5: Quantile. Quantile places the same number of features into each class. Use quantile for side-by-side or bivariate comparison of multiple indicators, as the scheme effectively reduces numerical attributes a similar ordinal scale, or when the median value is meaningful.

Annual Mean Level of Urban Fine PM ($\mu\text{g}/\text{m}^3$)

- 35.7–99.5
- 24.2–35.7
- 18.4–24.2
- 12.3–18.4
- 5.8–12.3

Missing data

The United Nations Sustainable Development Goals 29

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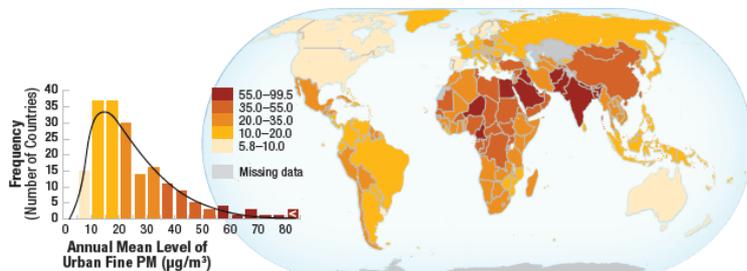
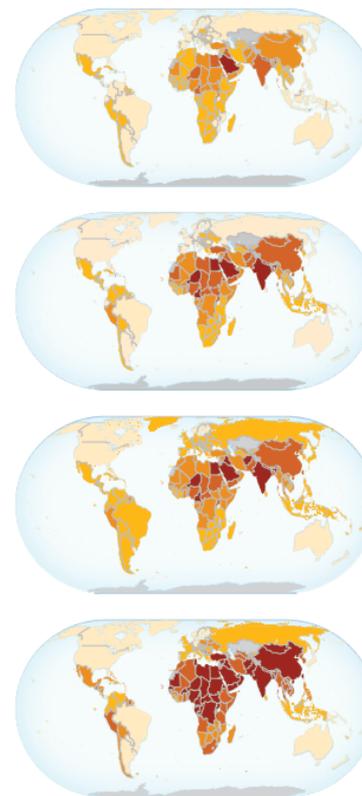


Figure 1.9-1: Data distributions and classification. **Left:** The histogram depicts the left-skewed attribute distribution for Indicator 11.6.2 (2016) on the annual mean levels of urban fine particulate matter. **Right:** The resulting arithmetic scheme increases distances between class breaks in a regular progress, here expanding each class width by $5 \mu\text{g}/\text{m}^3$, to provide more detail for features in the clustered side of the distribution, rather than emphasizing outliers.



Symbolisation describes the graphic encoding of geospatial data in the map. As cartography is a visual language, symbols are the words that cartographers

to encode the locational component of geospatial data in maps), size, shape, orientation, arrangement, texture, colour hue, colour value, colour saturation,

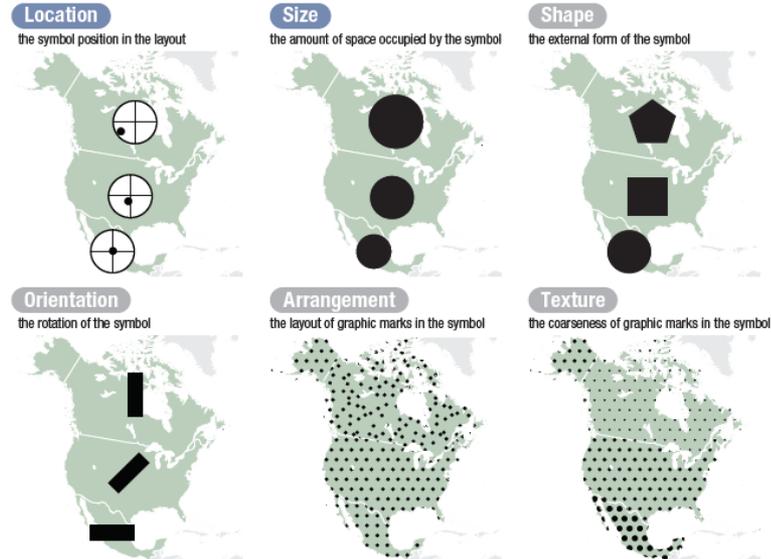
Visual Variables

The ways that a symbol can be modified to convey information; “the visual grammar”

tions are limited. The *visual variables* describe the ways that a symbol can be modified to convey information. Visual variables include location (logically used

seen by the eye such as small versus large (size) or light versus dark (colour value). This causes some symbol variations to rise to figure in the visual hierarchy (see

Figure 2.9-1: Visual variables and level of measurement. Colouring depicts the recommended use of each visual variable for numerical (both absolute and relative ratio and interval values), ordinal, and nominal levels of measurement.



Section 2.13). Other visual variables do not imply an order such as circle versus square (shape) or blue versus green (colour hue). Cartographers use this

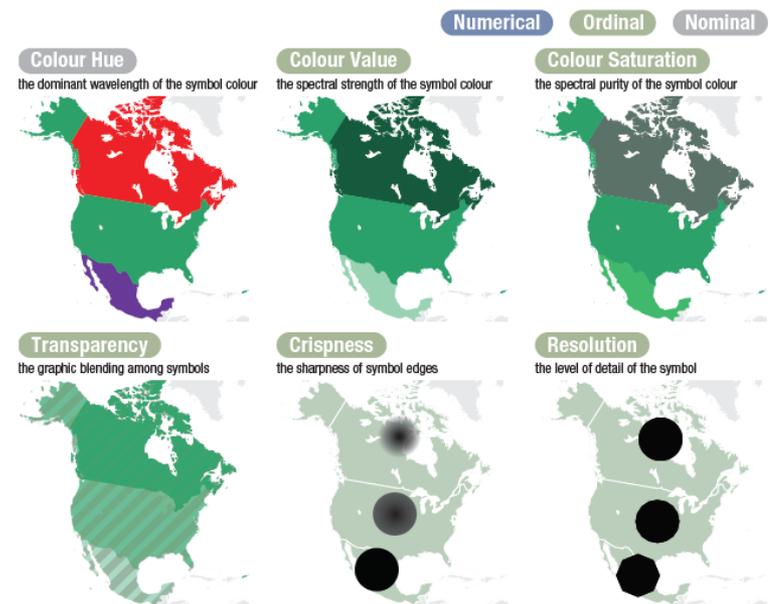
mended for encoding indicators that are collected at an ordinal level of measurement. Finally, besides location, the only *quantitative visual variable*

Symbolisation

The graphic encoding of geospatial data in the map; the “visual language”

a nominal level of measurement. *Ordered visual variables* such as colour value, colour saturation, transparency, crispness, and resolution are recom-

used for numerical data if transformed into an ordinal set of classes (see [Section 1.9](#)), a common solution for many thematic map types (see [Section 3.1](#)).



2.4 Map Projections

Map projection is the process of transferring geospatial data from a

A planar projection conceptually places the map surface on the globe,

SDG Mapping Best Practice #7

Use an equal-area projection for maps relying on relative amounts of colour or texture (e.g., nominal maps, choropleth maps)

any maps the map surface completely around the globe, with the unfurled surface resulting in a rectangular map. Because a normal cylindrical projection intersects the globe at or near the equator, they minimise distortion for regional maps of equatorial regions.

A conic projection conceptually wraps the map surface around one hemisphere of the globe, resulting in a semi-circular map. Normal conic projections minimise distortions for regional maps of the mid-latitudes.

angular relationships at infinity. Small points, heavily distorting areas as a result. Conformal projections often

are used as a shape of p two different result in d An equ projection pr polygon fi ing shape that rely d (e.g., chor

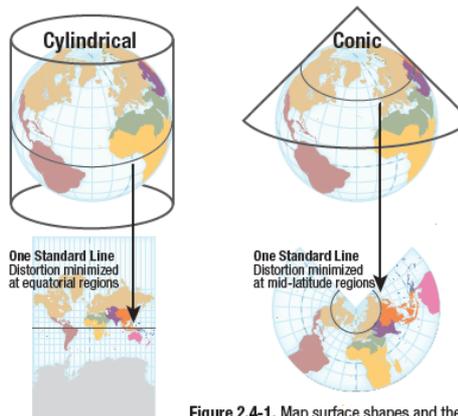


Figure 2.4-1. Map surface shapes and the cal. Middle: Conic. Right: Planar. Standard

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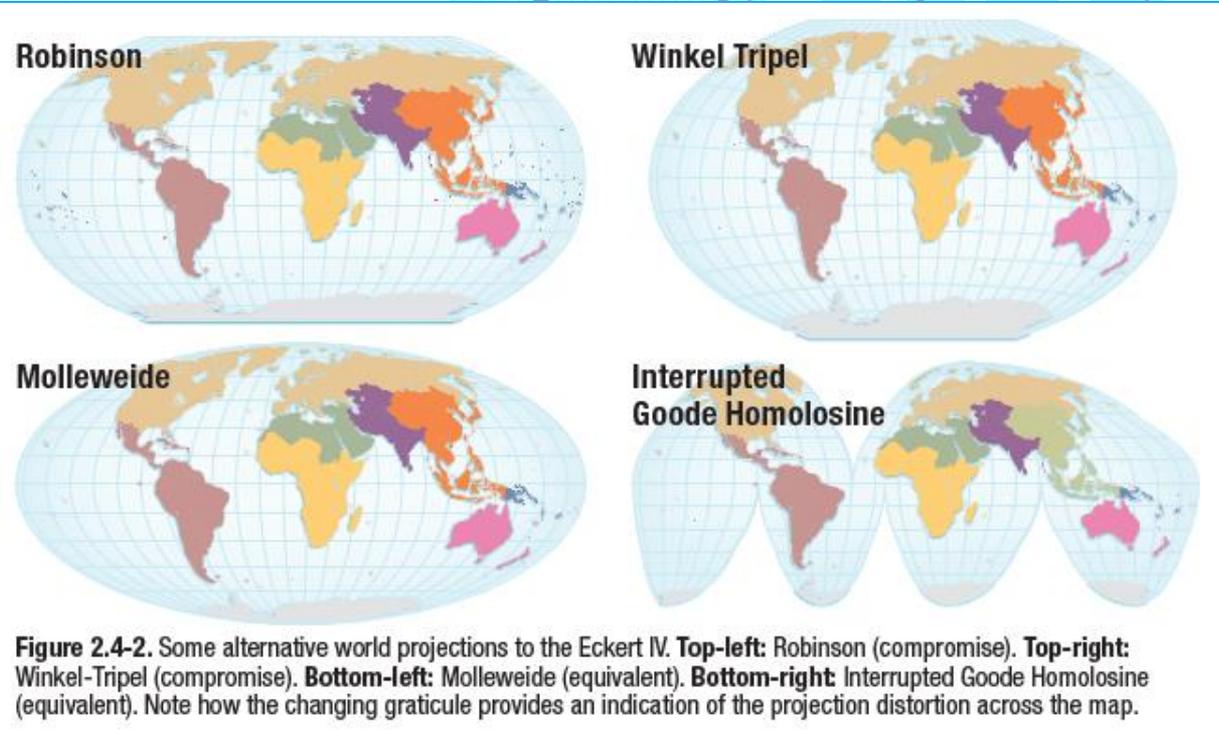
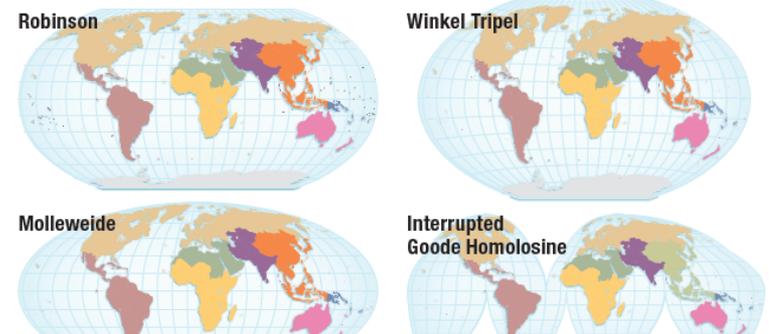
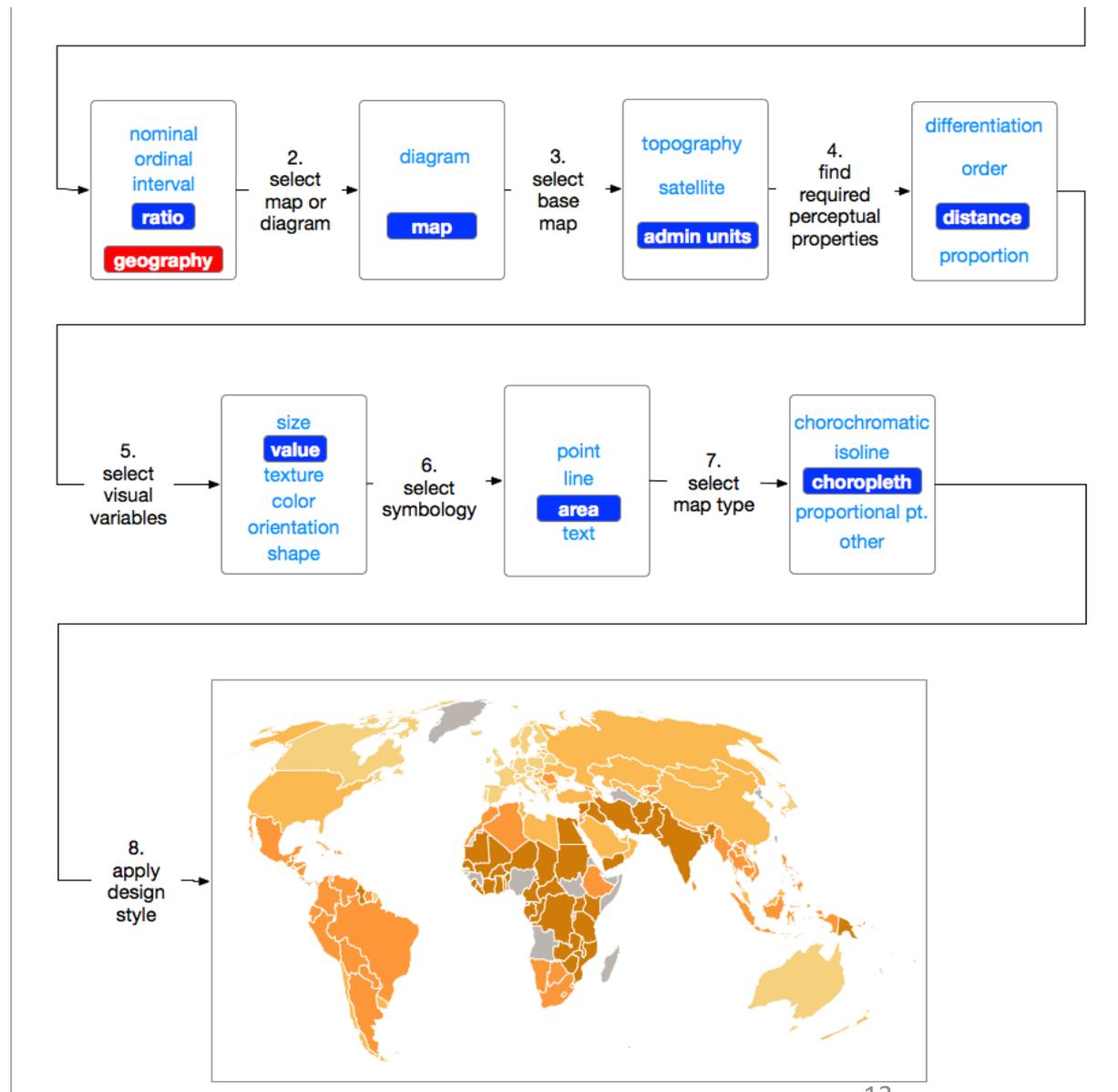


Figure 2.4-2. Some alternative world projections to the Eckert IV. **Top-left:** Robinson (compromise). **Top-right:** Winkel-Tripel (compromise). **Bottom-left:** Molleweide (equal-area). **Bottom-right:** Interrupted Goode Homolosine (equal-area). Note how the changing graticule provides an indication of the projection distortion across the map.



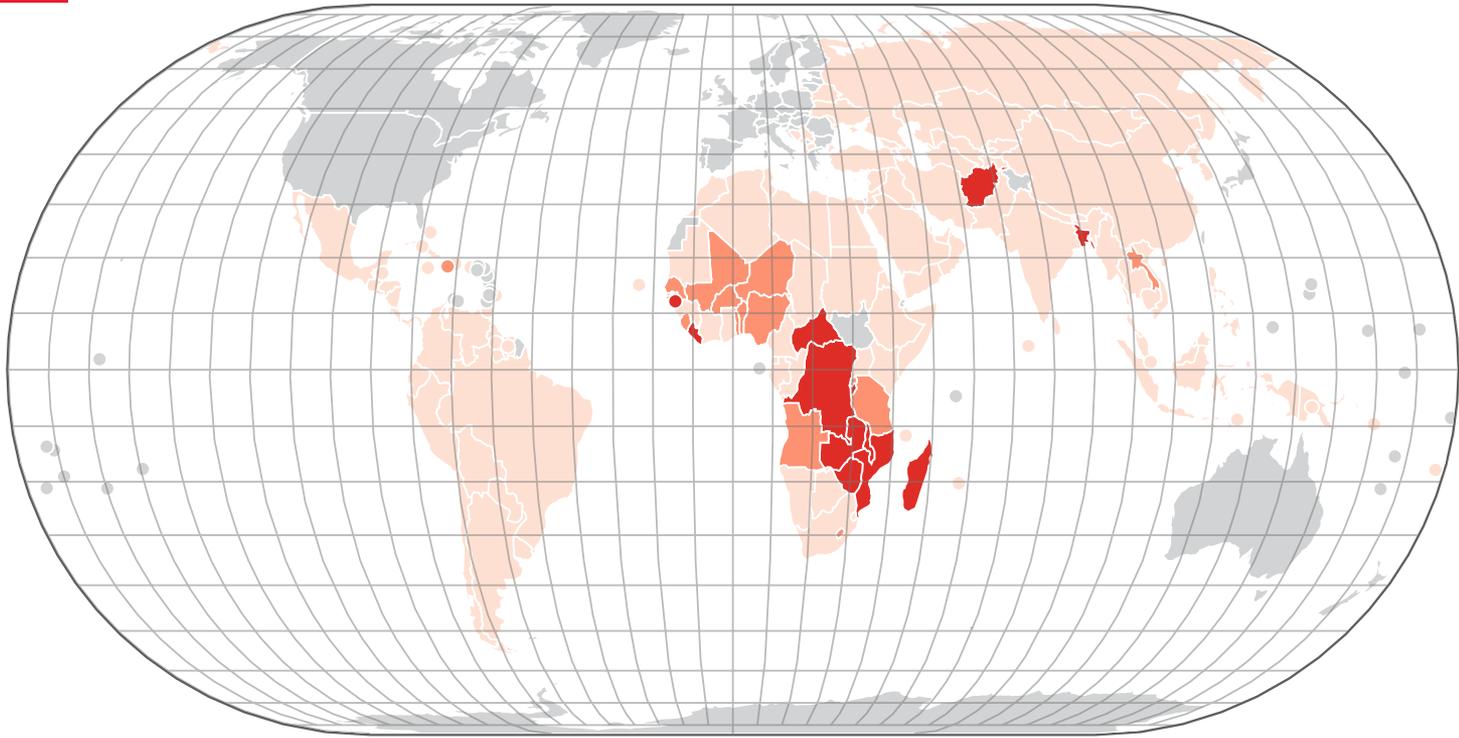
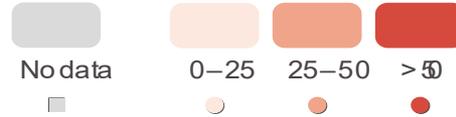
Decision making in the cartographic workflow



1 NO POVERTY



SDG Indicator 1.1.1: Proportion (%) of population below the international poverty line, 2016

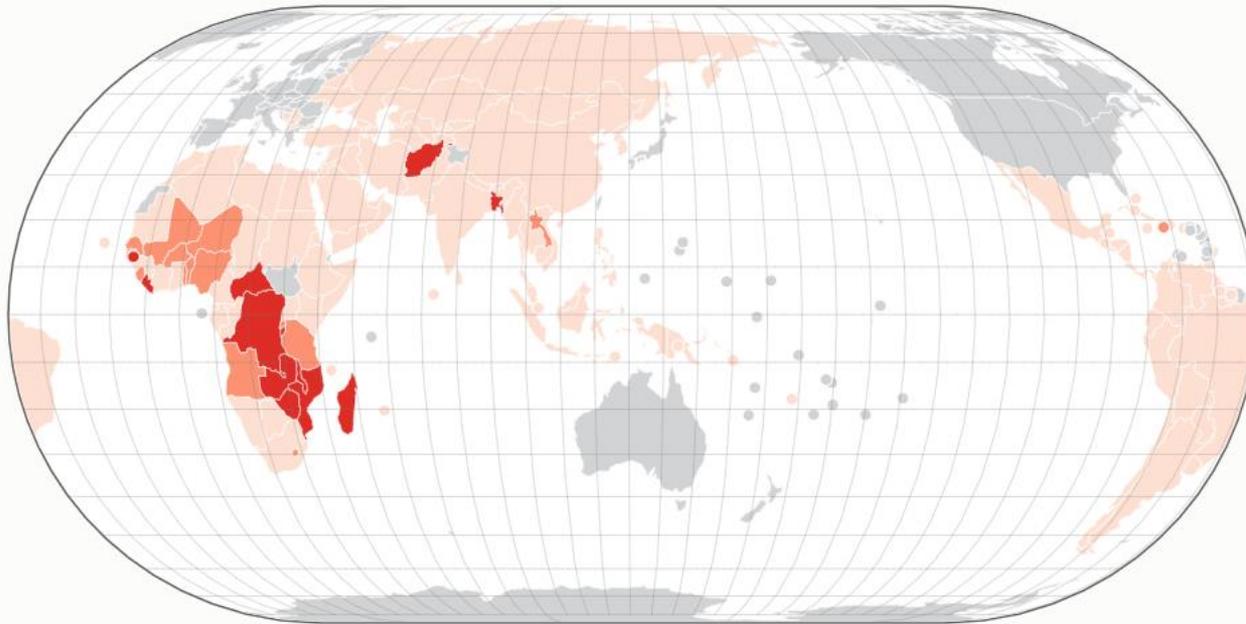
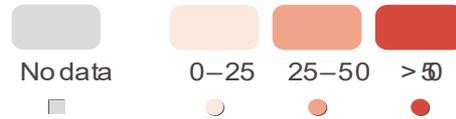


<https://gip-itc-universitytwente.github.io/SIDS/>

1 NO POVERTY



SDG Indicator 1.1.1: Proportion (%) of population below the international poverty line, 2016



Center coordinate: 131°

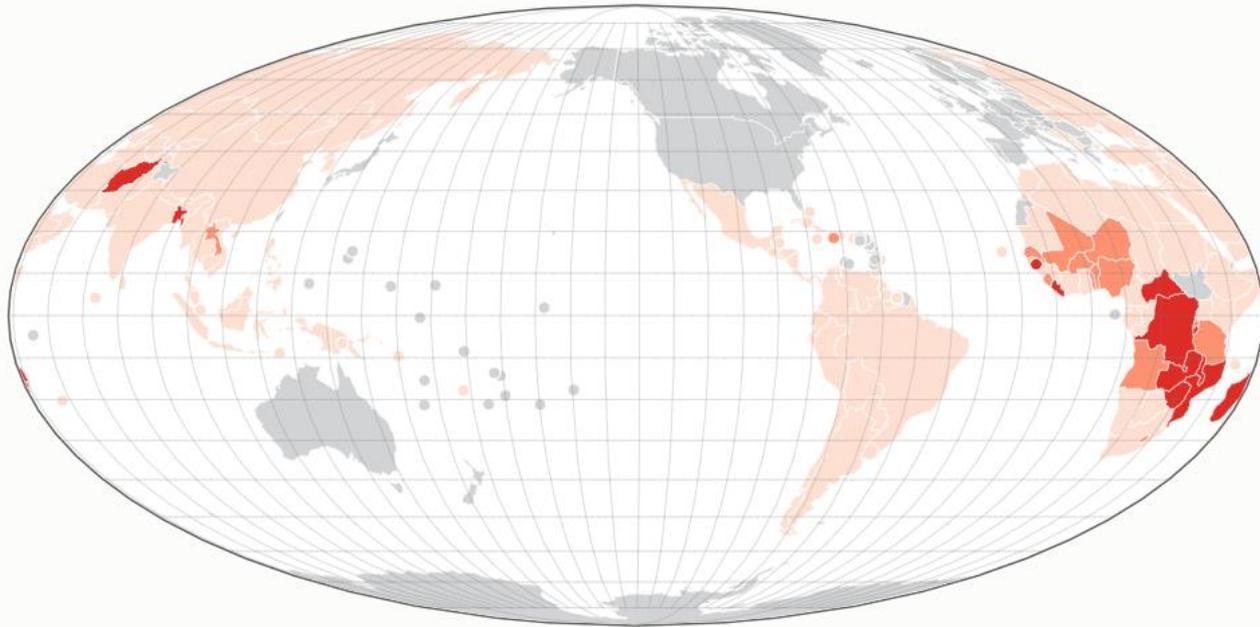
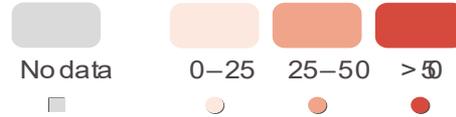
slide to change center

<https://gip-itc-universitytwente.github.io/SIDS/>

1 NO POVERTY



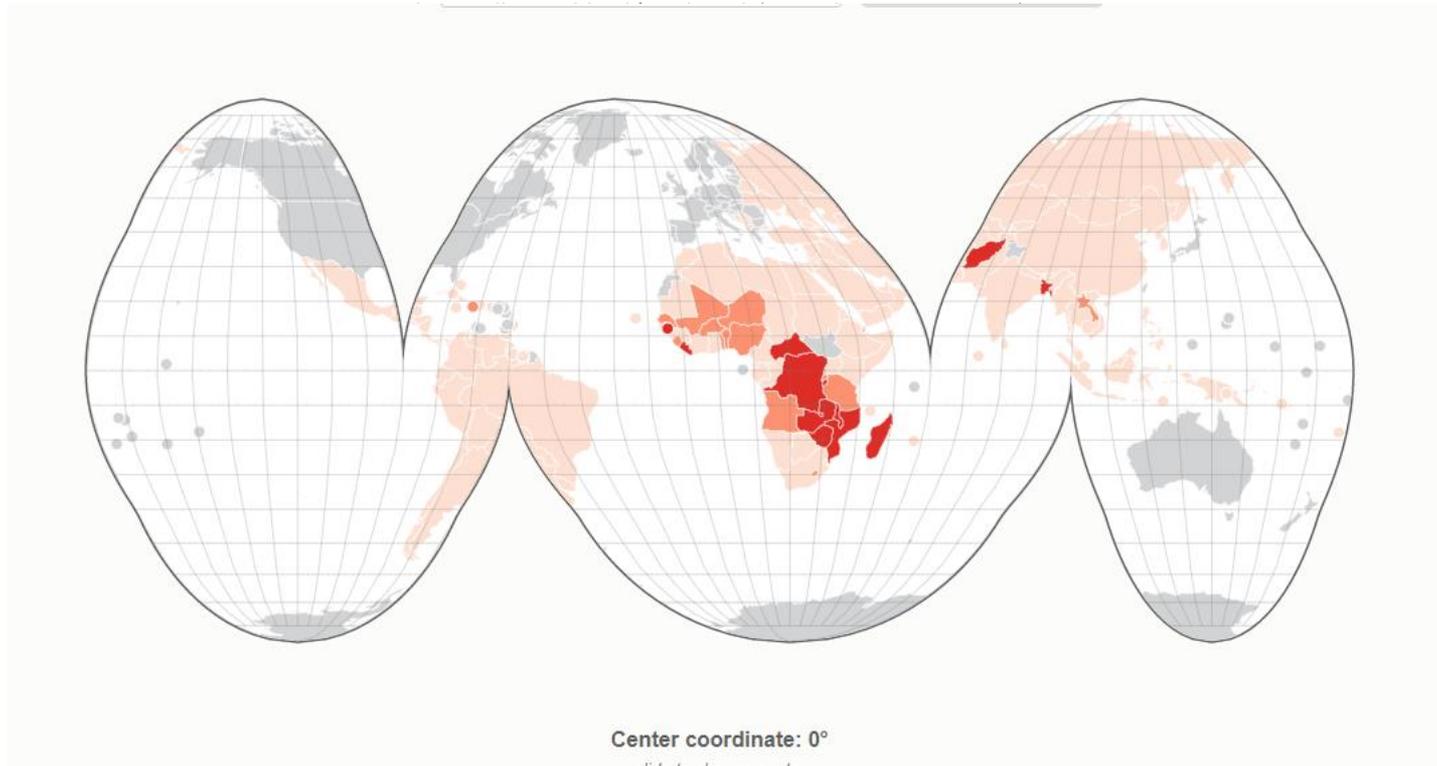
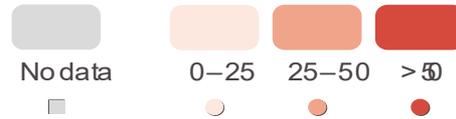
SDG Indicator 1.1.1: Proportion (%) of population below the international poverty line, 2016



1 NO POVERTY



SDG Indicator 1.1.1: Proportion (%) of population below the international poverty line, 2016



<https://gip-itc-universitytwente.github.io/SIDS/>

Color Scheme

Figure 2.10-2: Sequential colour scheme. Indicator 8.1.1 (2016) on the annual growth rate of real GDP per capita is mapped using a sequential colour scheme. Use a sequential colour scheme for ordinal data or classed numerical data with an apparent increase from low-to-high in one direction.

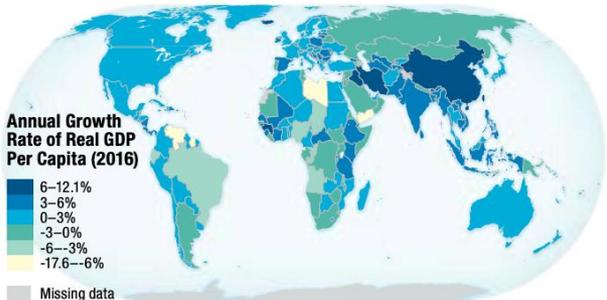


Figure 2.10-3: Diverging colour scheme. Indicator 8.1.1 (2016) is remapped with a more appropriate diverging colour scheme using zero per cent change as the critical midpoint. Use a diverging colour scheme for ordinal data or classed numerical data with an increase in two directions away from a critical value (e.g., zero, the mean or median).

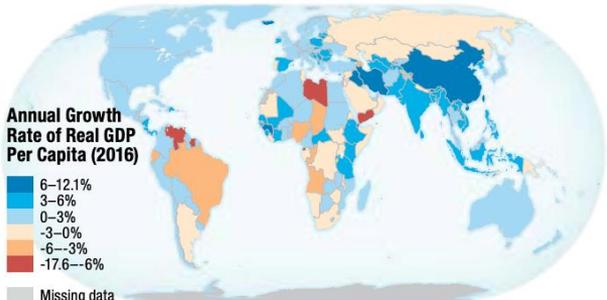
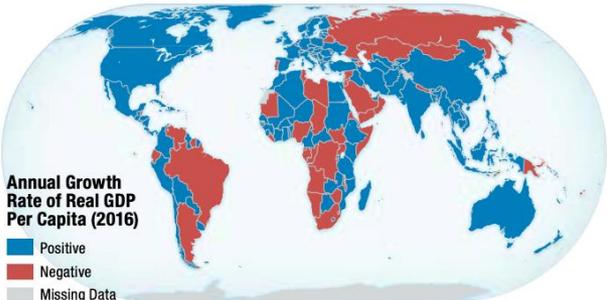


Figure 2.10-4: Qualitative colour scheme. Indicator 8.1.1 (2016) is transformed to a binary positive or negative change. Use a qualitative colour scheme for nominal data with no apparent ranked order (e.g., mode). Do not use a spectral colour scheme to map ordinal or numerical data, unless removing greens, to account for colour vision deficiency.

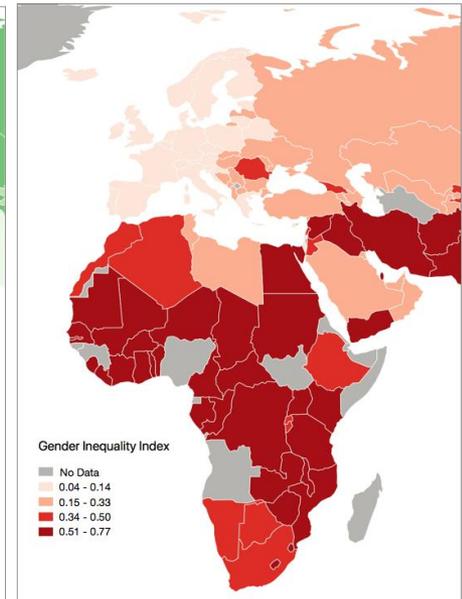
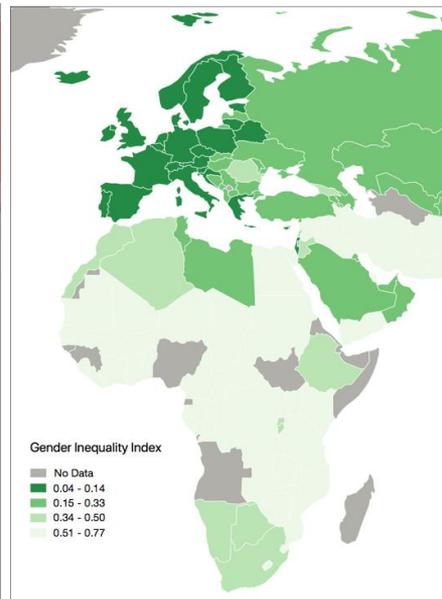
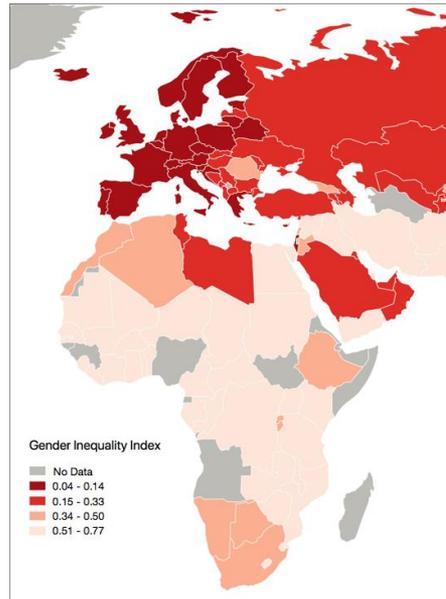
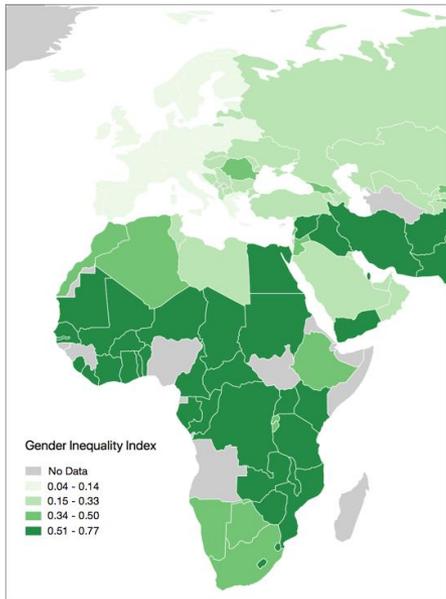


- Sequential
- Diverging
- Qualitative
- Ramp versus interval
- Need Help? [Color Brewer](#)

Choice of color

0 means there is no inequality

1 means a lot of inequality



SDG 15: Protect, restore and promote sustainable use of terrestrial ecosystems, sustainably manage forests, combat desertification, and halt and reverse land degradation and halt biodiversity loss

- 9 targets and 3 sub-targets – what is learned in this course could be used to address all 9 targets

Goal 15: Life on land

Target 15.1: By 2020, ensure the conservation, restoration and sustainable use of terrestrial and inland freshwater ecosystems and their services, in particular forests, wetlands, mountains and drylands, in line with obligations under international agreements

Indicator 15.1.2: Average proportion of Freshwater Key Biodiversity Areas (KBAs) covered by protected areas (percent)
Last updated last year | 744 Records

Search data and

landportal.org/pt/book/sdgs/151/indicador-1512

what is the method for measuring this indicator:

Selecione um indicador Seleccione un ano

Average proportion of Terrestrial Key Biodiversity Areas (KBAs) covered by protected areas (%)

2018

0 25 50 75 100

INDICATOR MIN-MAX NUMBER OF YEARS COUNTRIES / OBS MIN / MAX VALUE

Average proportion of Freshwater Key Biodiversity Areas (KBAs) covered by protected areas (%)	2000 / 2018 / 19	142 / 2698	0 / 100
Average proportion of Terrestrial Key Biodiversity Areas (KBAs) covered by protected areas (%)	2000 / 2018 / 19	234 / 4446	0 / 100

Series Name: Average proportion of Freshwater Key Biodiversity Areas (KBAs) covered by protected areas (%)
Series Code: ER_PTD_FRWRT

Links:
[Italian Government Official SDG 15.1.2](#)
[US Government Official SDG 15.1.2](#)
[United Nations Official SDG 15.1.2](#)
[International Union for the Conservation of Nature Background Information on Areas](#)

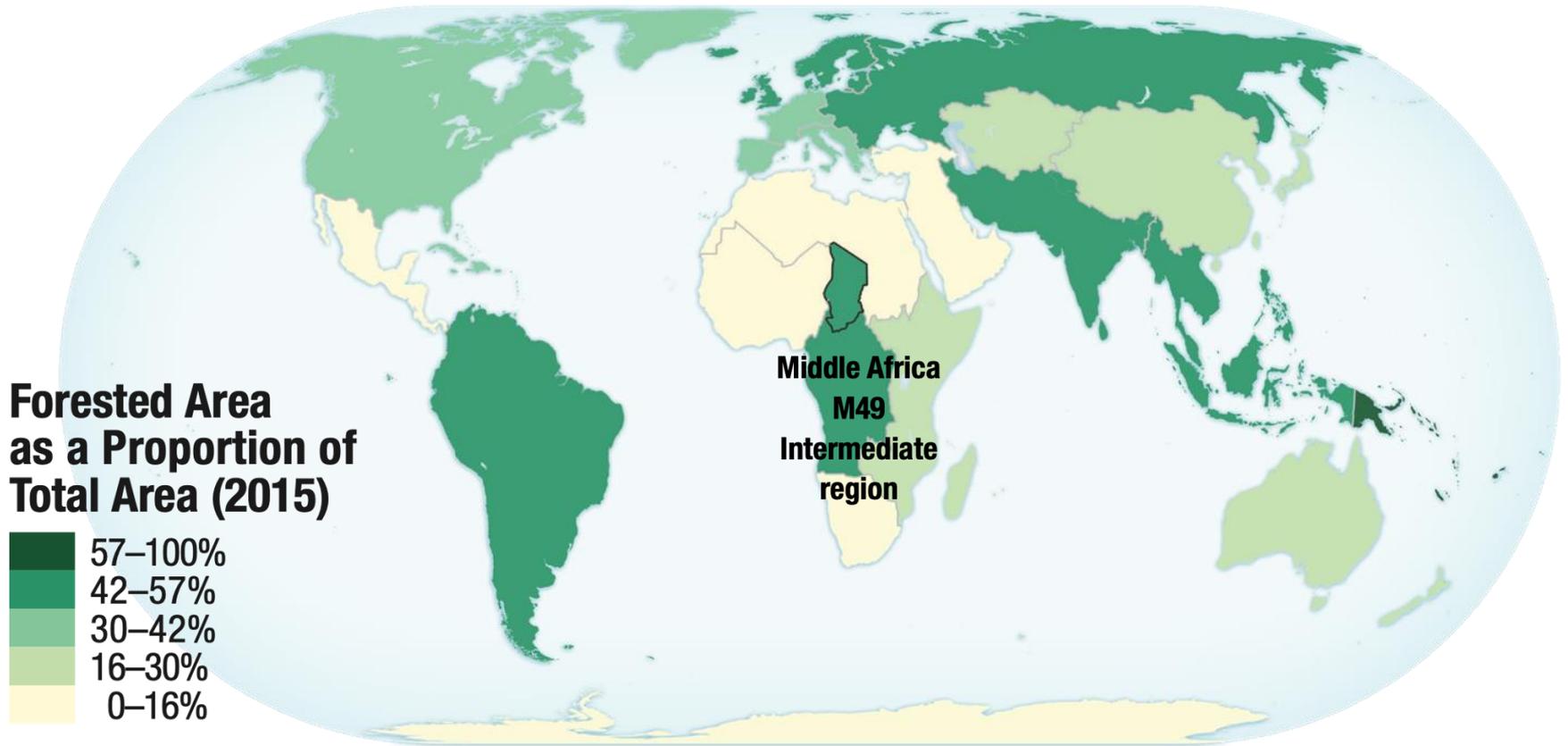
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 UNEP

Indicator 15.1.2: Average proportion of Freshwater Key Biodiversity Areas (KBAs) covered by protected areas (percent)



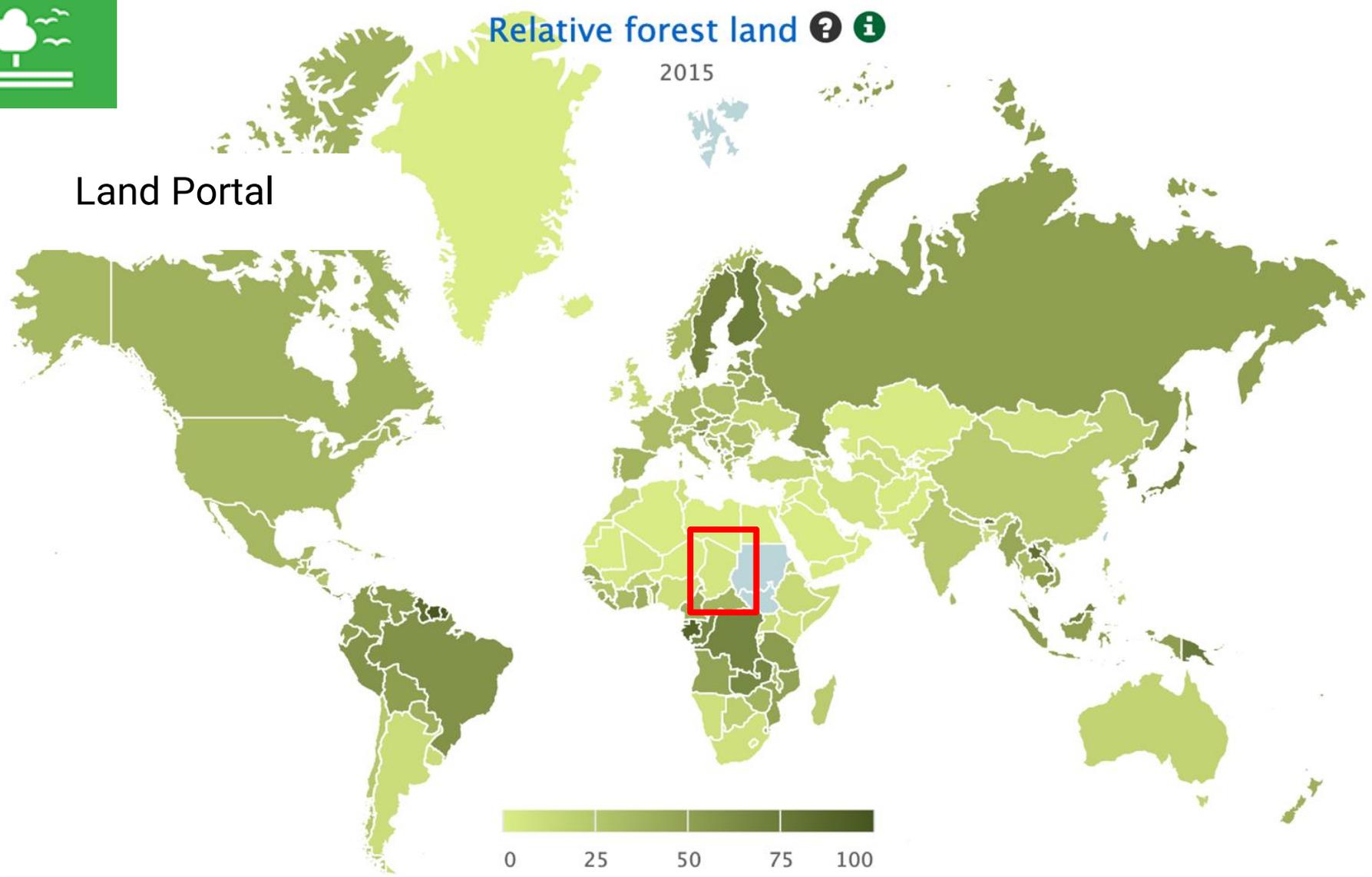
15.1.1



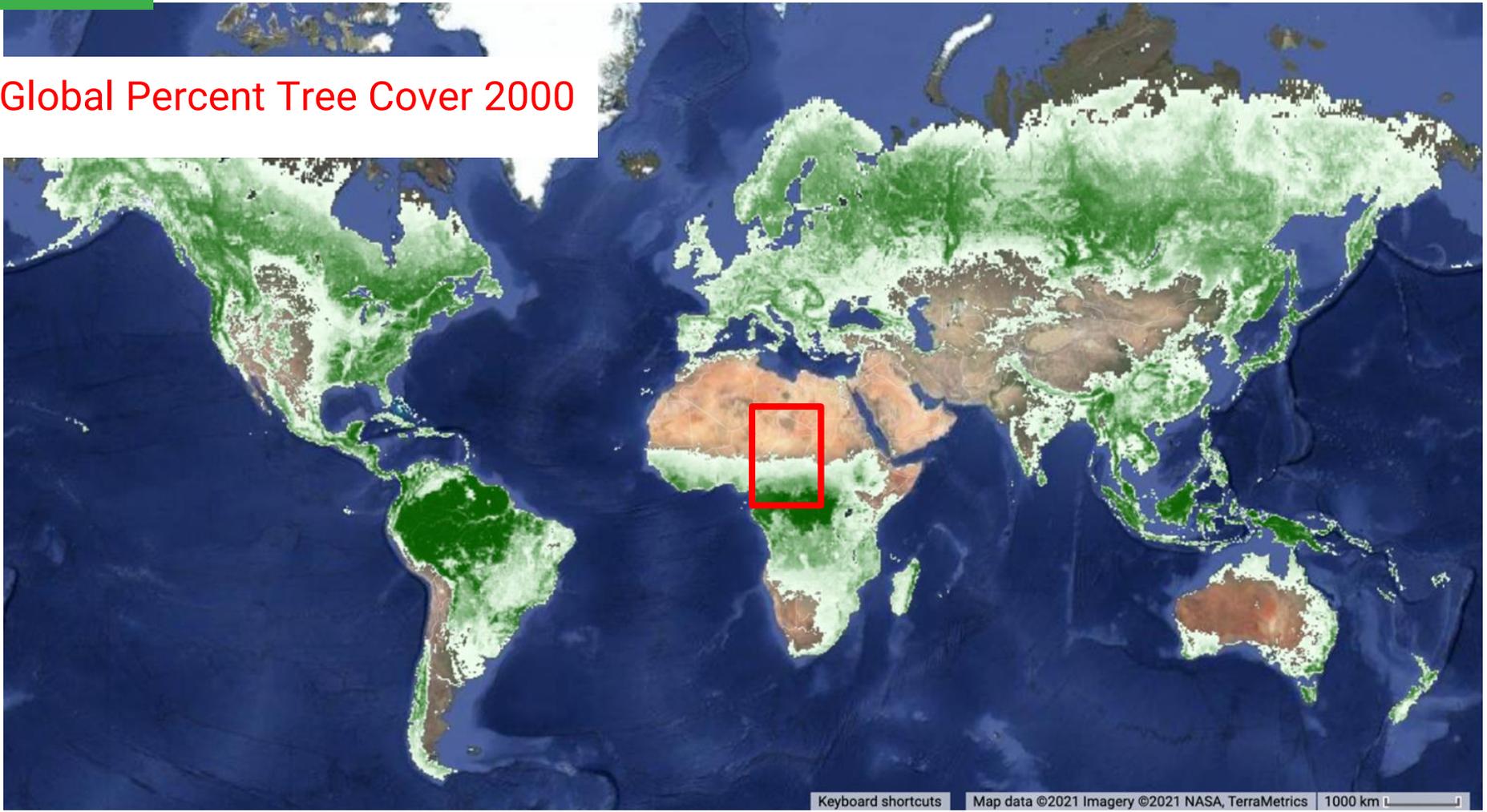
Relative forest land ? i

2015

Land Portal



Global Percent Tree Cover 2000





Region of interest: Boko Haram activity



2.1.1 Undernourished people per Sq KM

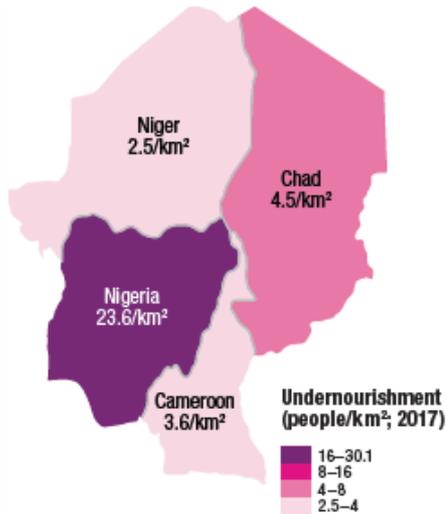


Figure 3.5-1: Original choropleth map. Indicator 2.1.1 (2017) on the number of undernourished people per km² is mapped for four countries in Sub-Saharan Africa.

Choropleth map



2.1.1 Undernourished people per Sq KM

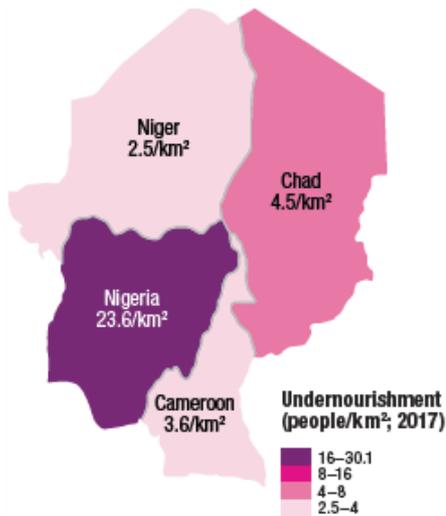


Figure 3.5-1: Original choropleth map. Indicator 2.1.1 (2017) on the number of undernourished people per km² is mapped for four countries in Sub-Saharan Africa.

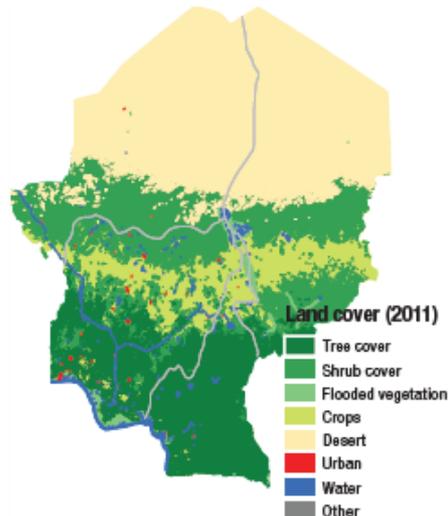


Figure 3.5-2: Exclusionary data. Classified land cover (2011) processed from satellite imagery is used to identify areas where people do not live: desert and water.

Binary Method



2.1.1 Undernourished people per Sq KM

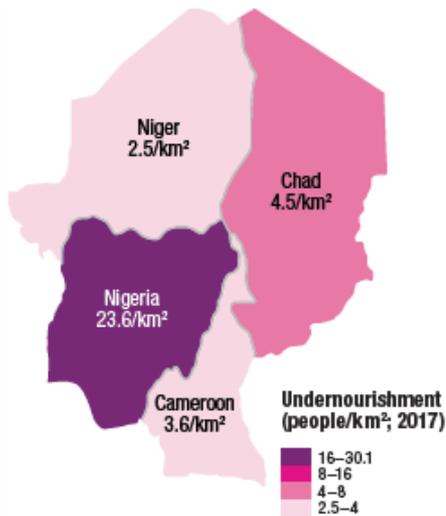


Figure 3.5-1: Original choropleth map. Indicator 2.1.1 (2017) on the number of undernourished people per km² is mapped for four countries in Sub-Saharan Africa.

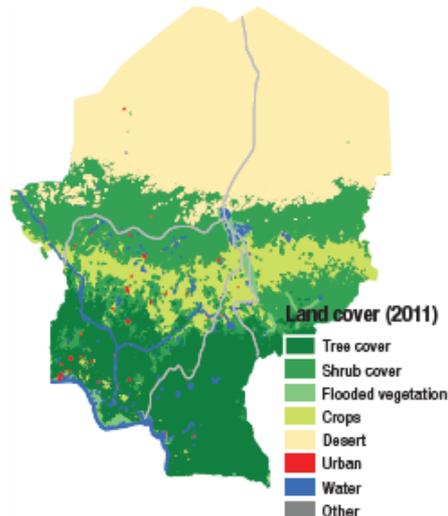


Figure 3.5-2: Exclusionary data. Classified land cover (2011) processed from satellite imagery is used to identify areas where people do not live: desert and water.

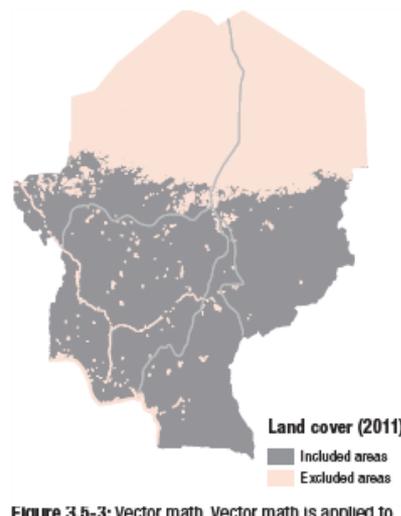


Figure 3.5-3: Vector math. Vector math is applied to remove the desert and water classes from the enumeration unit. Large areas in the north are removed due to the location of the Sahara Desert as well as smaller water bodies such as Lake Chad and the Niger River.

Binary Method:
Omit area where people do not live



2.1.1 Undernourished people per Sq KM

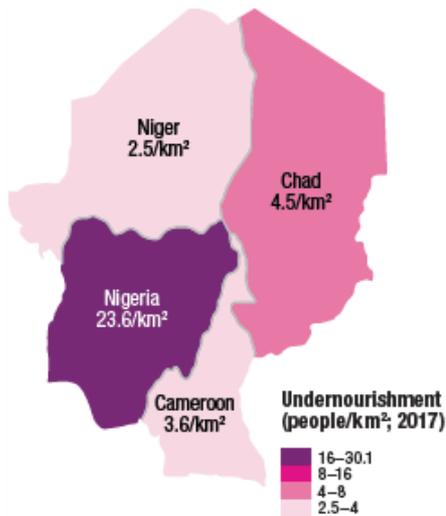


Figure 3.5-1: Original choropleth map. Indicator 2.1.1 (2017) on the number of undernourished people per km² is mapped for four countries in Sub-Saharan Africa.

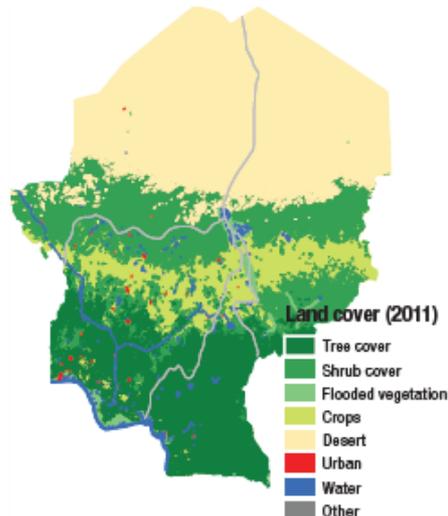


Figure 3.5-2: Exclusionary data. Classified land cover (2011) processed from satellite imagery is used to identify areas where people do not live: desert and water.

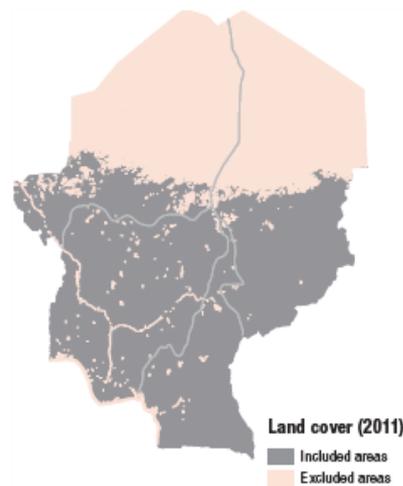


Figure 3.5-3: Vector math. Vector math is applied to remove the desert and water classes from the enumeration unit. Large areas in the north are removed due to the location of the Sahara Desert as well as smaller water bodies such as Lake Chad and the Niger River.

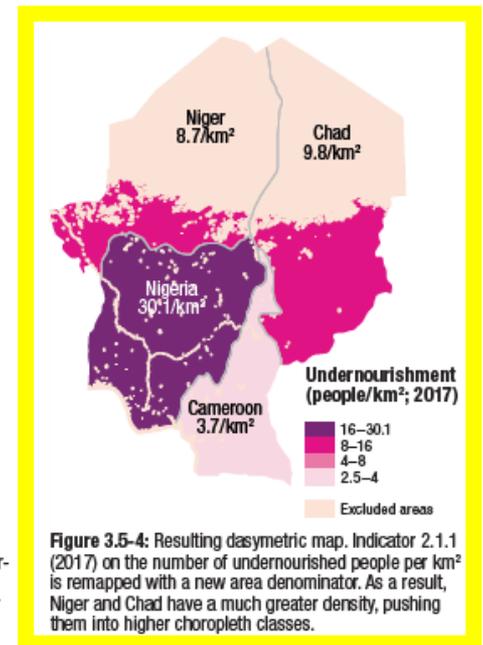


Figure 3.5-4: Resulting dasymetric map. Indicator 2.1.1 (2017) on the number of undernourished people per km² is remapped with a new area denominator. As a result, Niger and Chad have a much greater density, pushing them into higher choropleth classes.



Article

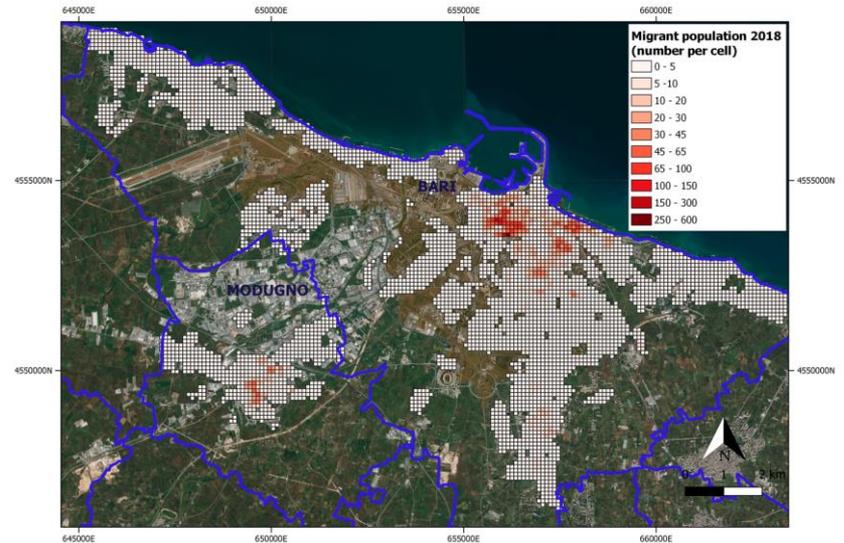
Earth Observation for the Implementation of Sustainable Development Goal 11 Indicators at Local Scale: Monitoring of the Migrant Population Distribution

Mariella Aquilino ^{1,2,*}, Cristina Tarantino ¹, Maria Adamo ¹, Angela Barbanente ² and Palma Blonda ¹

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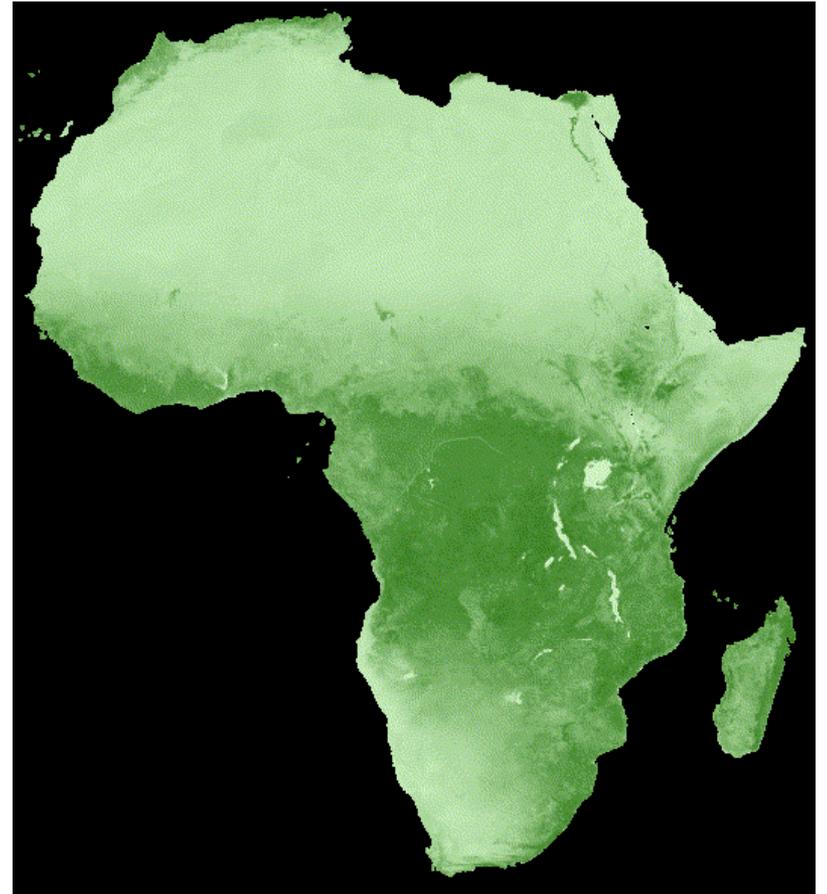
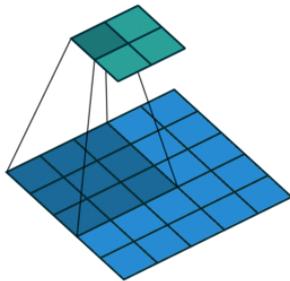
² Department of Civil, Environmental, Land, Building Engineering and Chemistry (DICATECh), Polytechnic University of Bari, Via Orabona 4, 70125 Bari, Italy; angela.barbanente@poliba.it

* Correspondence: aquilino@iia.cnr.it

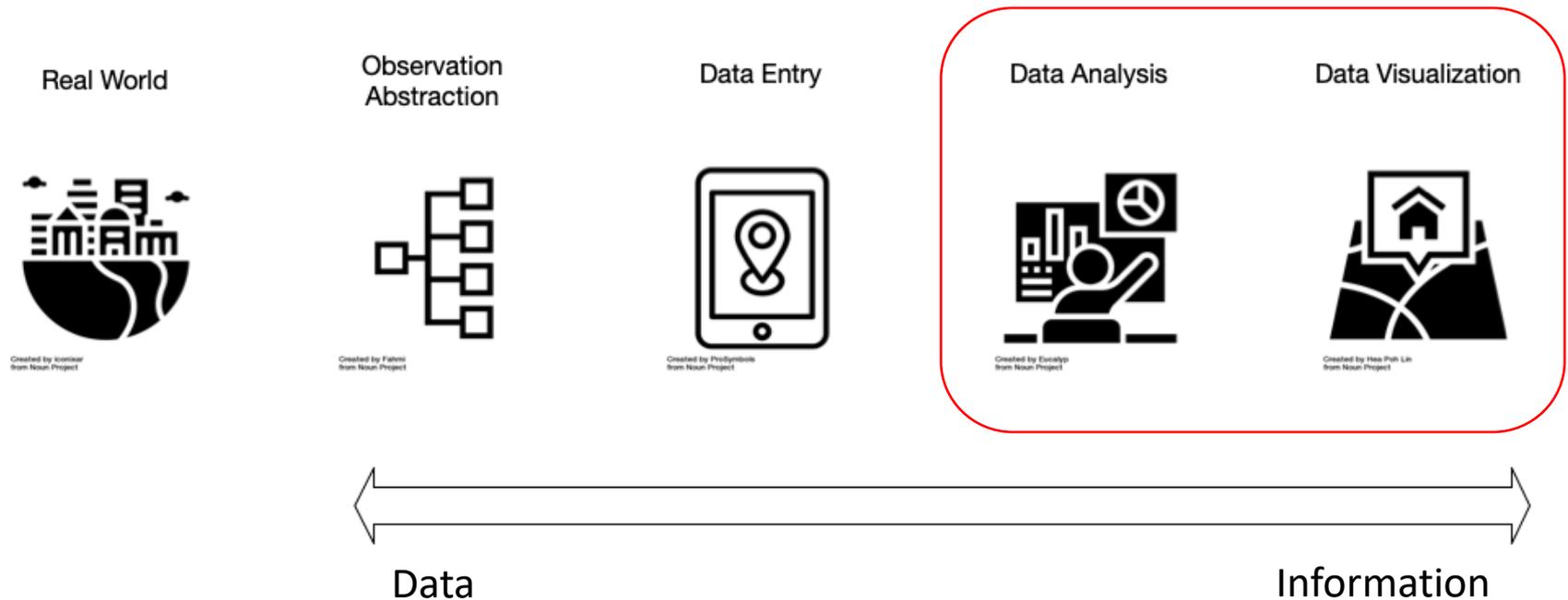


Possible ancillary data to combine with SDG data

NDVI over one year

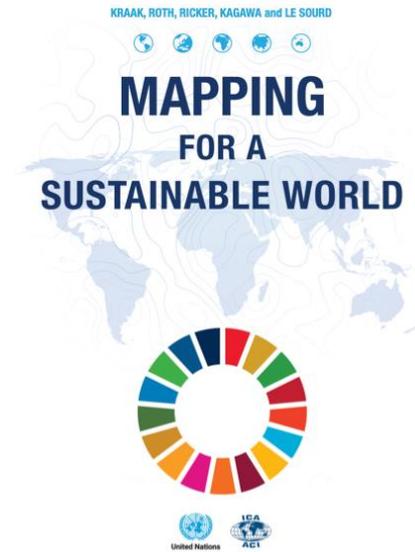


Data Provenance: How spatial indicators are collected and then mapped



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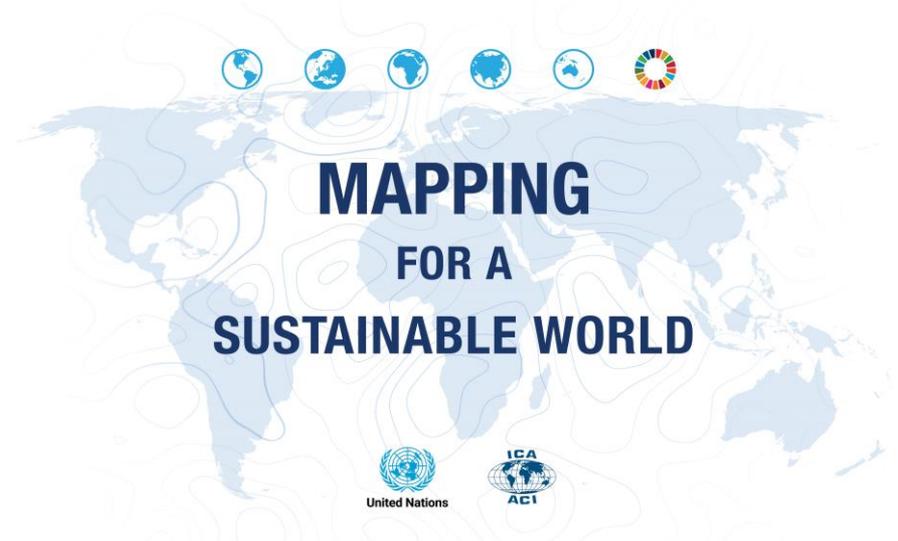
[Mapping for a sustainable world / \(un.org\)](https://www.un.org/)



Utrecht University

Thank you!

Britta Ricker @bricker



UNITED NATIONS Geospatial
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